FRANKFURT UNIVERSITY OF APPLIED SCIENCES

IoT Project
Introduction

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https://teaching.dahahm.de

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Agenda

Agenda

About me

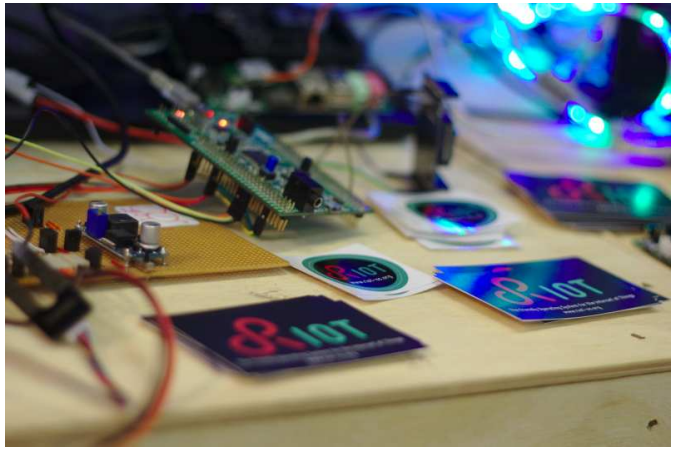
- Study of Computer Science at Freie Universität Berlin
- Software Developer for ScatterWeb and Zühlke Engineering
- Research on IoT and Operating Systems

Contact

E-mail: oliver.hahm@fb2.fra-uas.de
Office hours: Fridays 10:00 – 11:00, room 1-212

Join the RIOT!

RIOT is the friendly operating system for the IoT!



You're interested in ...

- ... programming the IoT?
- ... collaborate with hundreds of people from all over the world?
- ... contribute to a big FLOSS project?

Get in touch

Get in touch and do some hacking at the **All RIOT** event at the university!
Every two or three weeks 4pm in room 1-237.

Or look at `https://riot-os.org/community.html`

What about you?

- What is your motivation for this course?
- What do you think about the Internet of Things?

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What?

- Create a firmware based on RIOT (`https://riot-os.org`)
- The firmware should periodically read sensor data and send it towards an IoT Cloud provider
- Sending data to the cloud requires ...
  - a **border router**
  - multi-hop forwarding towards the border router
- Create a driver for an emulated sensor

How?

- Team work (two students per group)
- Each team work on a common code base
- git is used as version control system
- Write documentation about your project
- Run (and evaluate) your code on the FIT IoT-Lab
- Present your work

What (and when) to Submit?

- February 07, 2023: Presentation
  - Give a short presentation on your work (live demo?)
- February 10, 2023: Submission
  - Final version of the code is in the repository

  → You have granted access to me
  - Send me your documentation

Further Information

Course page

All material regarding this course can be found at
https://teaching.dahahm.de

This includes

- Announcements
- Slides
- Dates

campUAS

Enrolment Key:
`HahmDigi`

Additional Sources

Everything related to RIOT can be found at https://riot-os.org .
All information about the IoT-Lab testbed facility can be found at
https://iot-lab.info .

Agenda

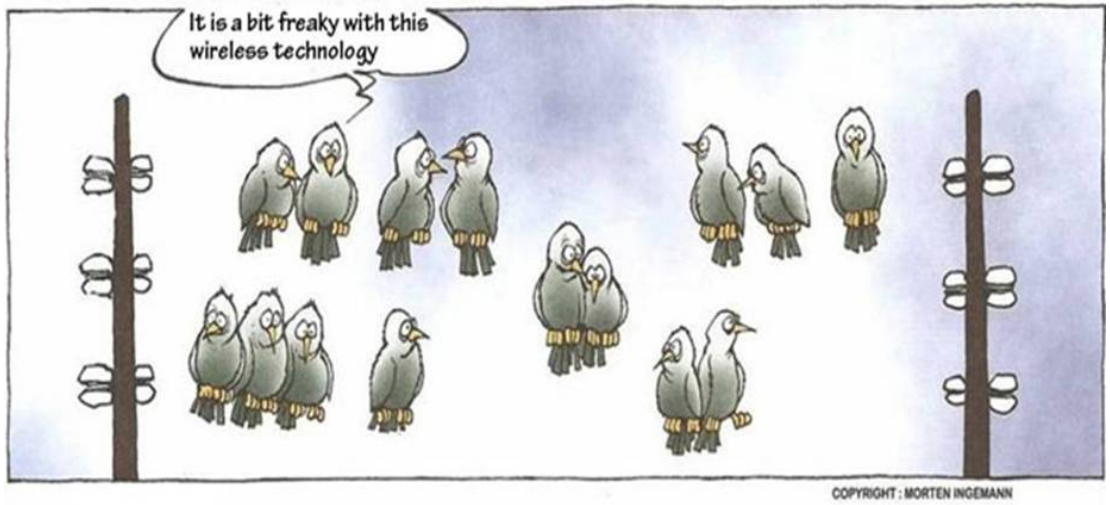
The Evolution of the IoT

Three Disruptive Technologies as the Roots of the IoT

The Evolution of the IoT

Three Disruptive Technologies as the Roots of the IoT

- Wireless Communication
- Low-cost Embedded Systems
- The Internet



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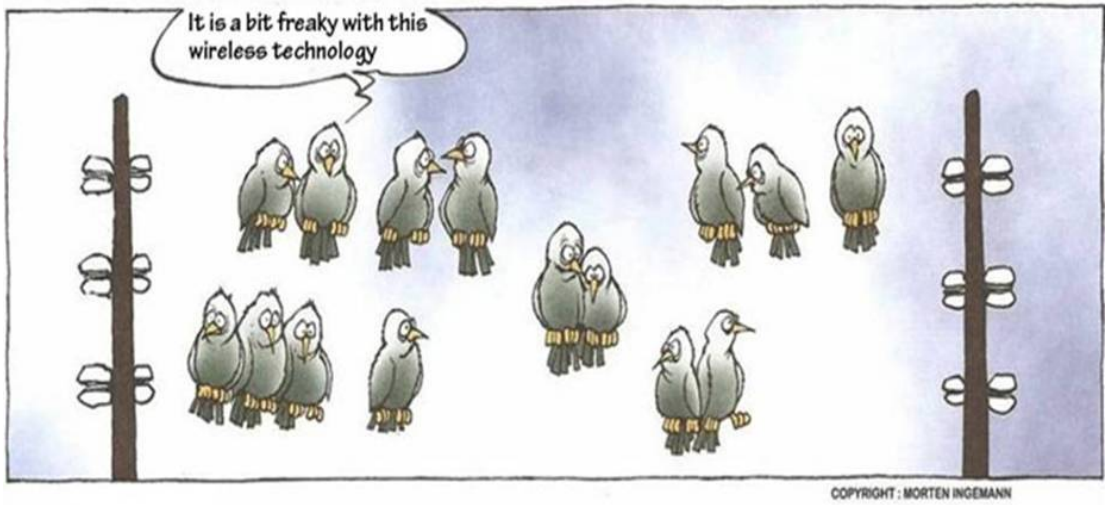

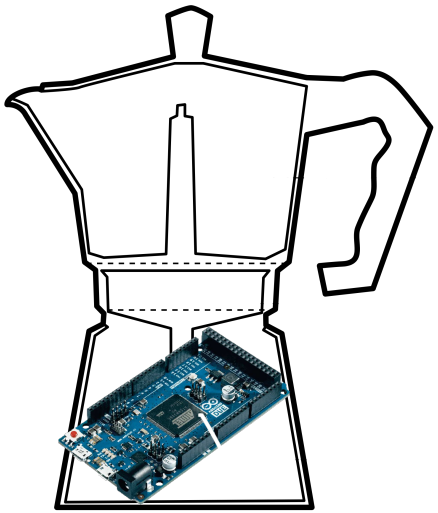

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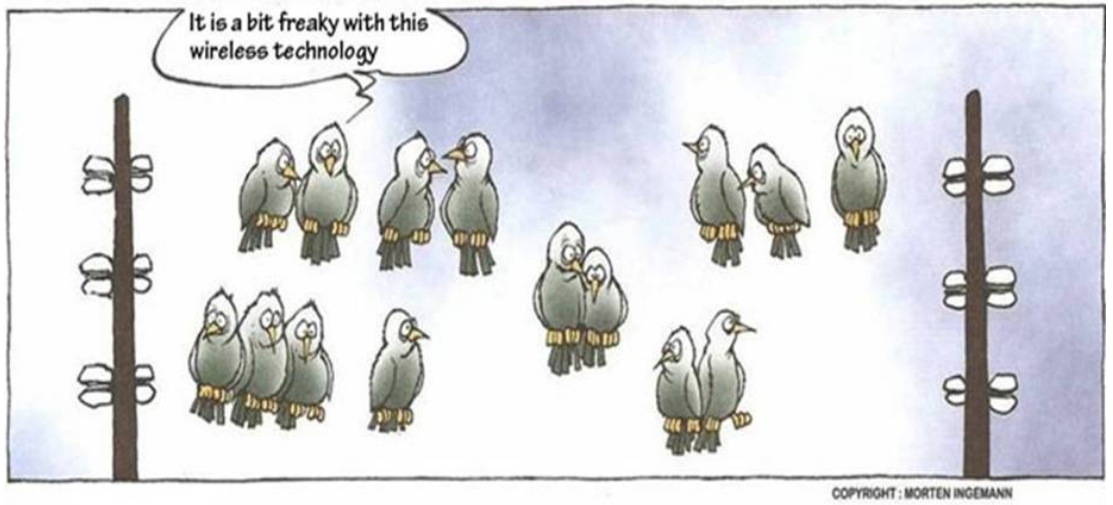
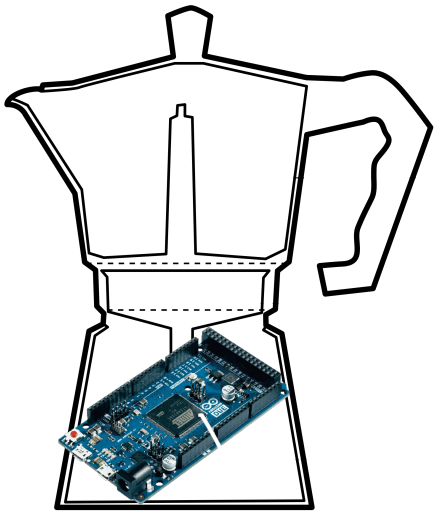




Smart Object Networking at Internet-Scale

Connecting the Physical World with the Internet

- Transforming Things into Smart Objects
- Enabling Interconnected Smart Services

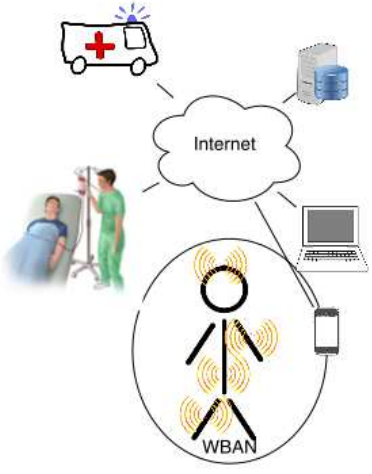
Smart Object Networking at Internet-Scale

Industrial Automation

Connecting the Physical World with the Internet

- Transforming Things into Smart Objects
- Enabling Interconnected Smart Services

Mobile Health



Micro & Nano Satellites

Building & Home Automation

Use Case Requirements

- Interoperability
- Energy Efficiency
- Reliability
- Latency
- Low Cost Factor
- Autonomy
- Security
- Scalability

It ain't smart if I have to charge it every day

Agenda

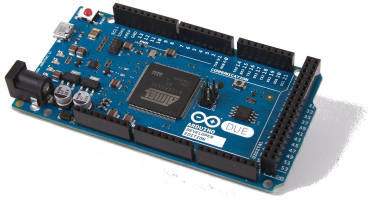
Requirements for IoT Software

Low-end IoT Devices: Limited Resources (RFC7228)

iotlab-m3

Senslab
WSN430

Arduino Due



- Memory $<$ 1 Mb
- CPU $<$ 100 MHz
- Energy $<$ 10 Wh

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iotlab-m3

Senslab WSN430

Arduino Due

- Memory $<$ 1 Mb
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$+$

Use Case Requirements

$=$

Software Requirements

- Energy Efficiency
- Sustainability
- Network Connectivity
- Real-Time Capabilities
- Small Memory Footprint
- Security and Safety
- Support for Heterogeneous Hardware

Embedded Operating Systems

No User Interaction

- No GUI required ⇒ No Pseudo-Parallel Execution is required
- Must Operate Autonomously → Must Recover from Errors
- Autoconfiguration is required

Source: Embedded Lab, https://www.electronics-lab.com/

[1] Memory Management Unit
[2] Floating Point Unit

Embedded Operating Systems

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- No GUI required ⇒ No Pseudo-Parallel Execution is required
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Constrained Hardware

- Often no MMU[1] and no FPU[2]
- Typically no Display or Input Devices
- In many cases no Persistent Memory

Source: Embedded Lab, https://www.electronics-lab.com/

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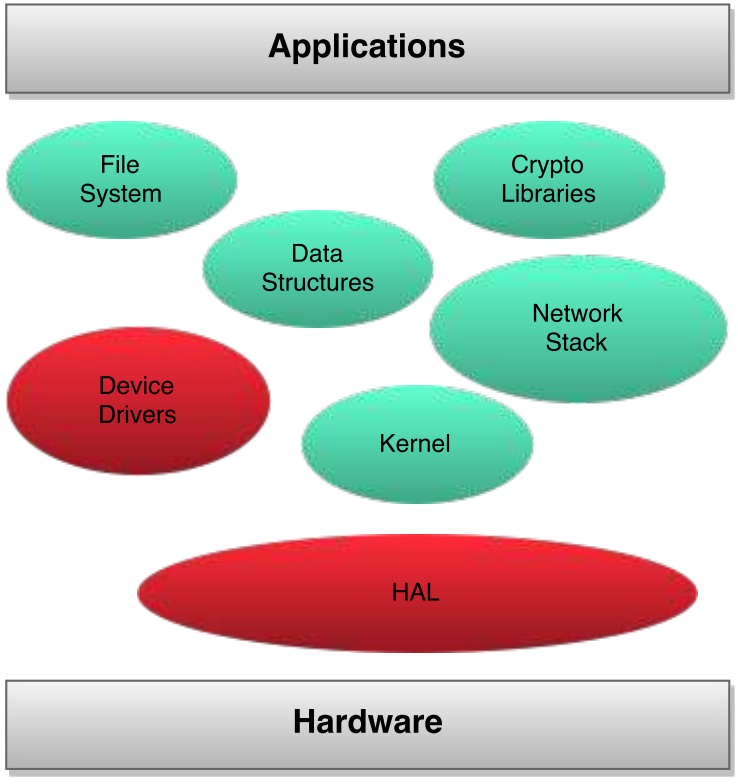
Source: Embedded Lab, https://www.electronics-lab.com/

- No Multi-User Support required
- Often only one Application
- Typically no dynamic linking → just one statically linked binary

[1] Memory Management Unit
[2] Floating Point Unit

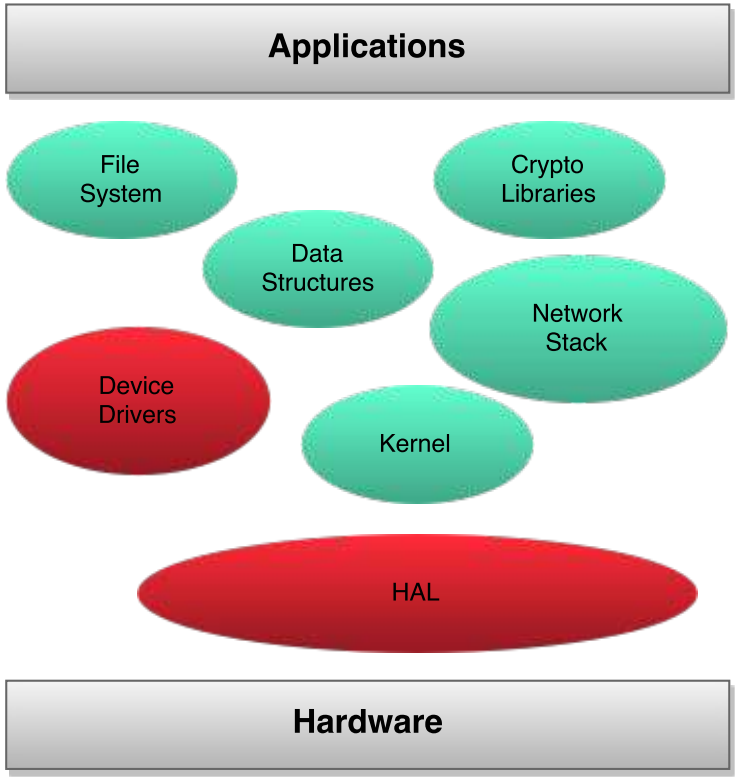
The Need for an OS for Low-end IoT Devices

Unified Software Platform

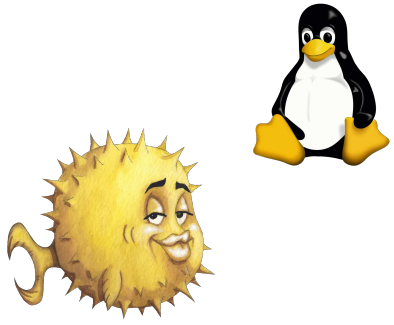


The Need for an OS for Low-end IoT Devices

Unified Software Platform



Open Source



Operating Systems for Low-End IoT Devices: Linux

Full-fledged OS

Does not fit

- Too Big
- Requires a MMU
- Not Targeted for Real-Time or Low-Energy

Operating Systems for Low-End IoT Devices: Linux

Full-fledged OS

WSN OS

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Too Complicated

- Hard to Learn
- No System Level Compatibility

Operating Systems for Low-End IoT Devices: Linux

Full-fledged OS

WSN OS

RTOS

Does not fit

- Too Big
- Requires a MMU
- Not Targeted for Real-Time or Low-Energy

Too Complicated

- Hard to Learn
- No System Level Compatibility

Too Minimalistic

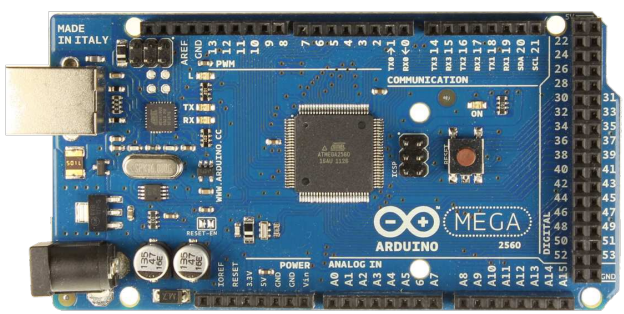
- No Built in Networking Support
- No Common API

Agenda

The friendly OS for the IoT

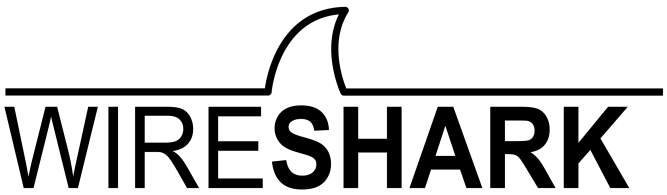
"If your IoT device cannot run Linux, then use RIOT!"

- RIOT requires only a few kB of RAM/ROM, and a small CPU
- With RIOT, code once & run heterogeneous IoT hardware
  - 8bit hardware (e.g. Arduino)
  - 16bit hardware (e.g. MSP430)
  - 32bit hardware (e.g. ARM Cortex-M, x86)



Open Standards, Open Source

- Free, open source (LGPLv2.1) operating system for constrained IoT devices
- Write your code in ANSI-C or C++
- Compliant with the most widely used POSIX features like pthreads and sockets
- No IoT hardware needed for development
- Run & debug RIOT as native process in Linux



Programming Language and Guidelines

Important Programming Language Properties

- No Overhead
- Full Control over Memory Management
- Direct Access to the Hardware
- Binding to other Languages
- Usability

Why C?

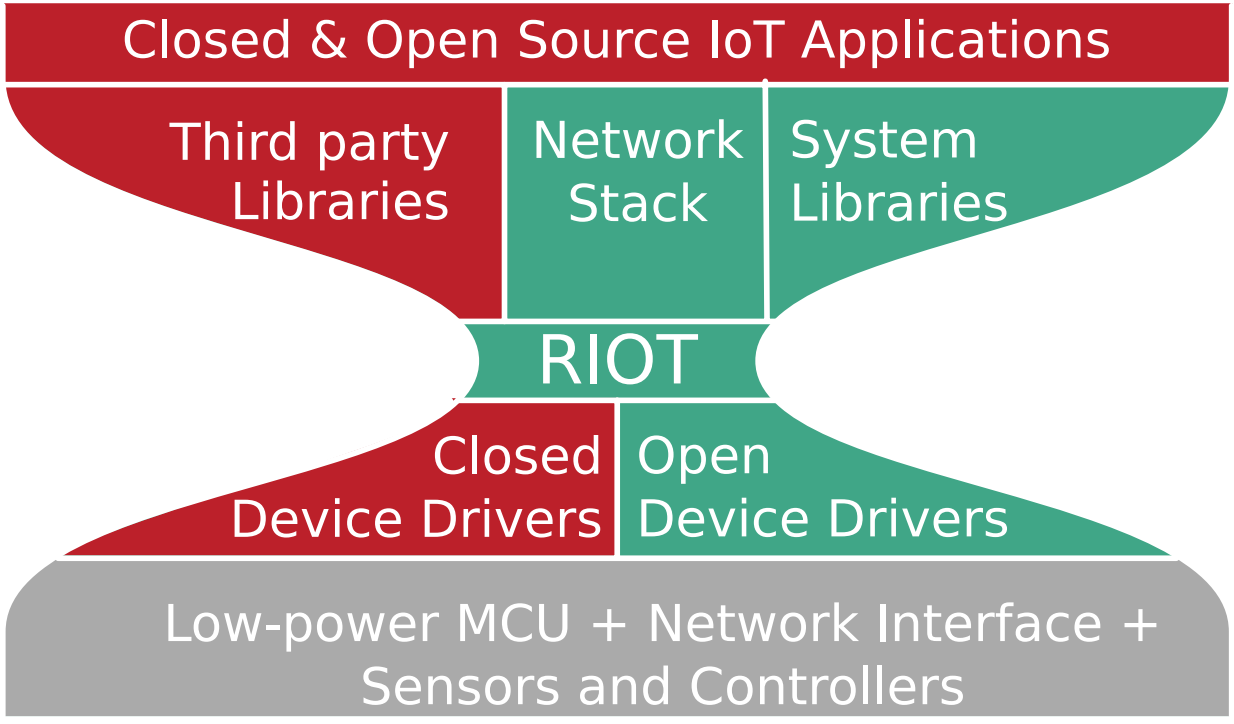
- Ticks all the Boxes
- Stable Specification
- Widely Used → Tooling

```
140 void thread_yield(void)
141 {
142     unsigned old_state = irq_disable();
143     thread_t *me = thread_get_active();
144
145     if (me->status >= STATUS_ON_RUNQUEUE) {
146         sched_runq_advance(me->priority);
147     }
148     irq_restore(old_state);
149
150     thread_yield_higher();
151 }
```

Programming Guidelines

- Follow a Structured and Procedural Approach
- Keep It Simple, Stupid (KISS)
- No Dynamic Memory Allocation
- Be Resource-aware
- No Macro “Magic”

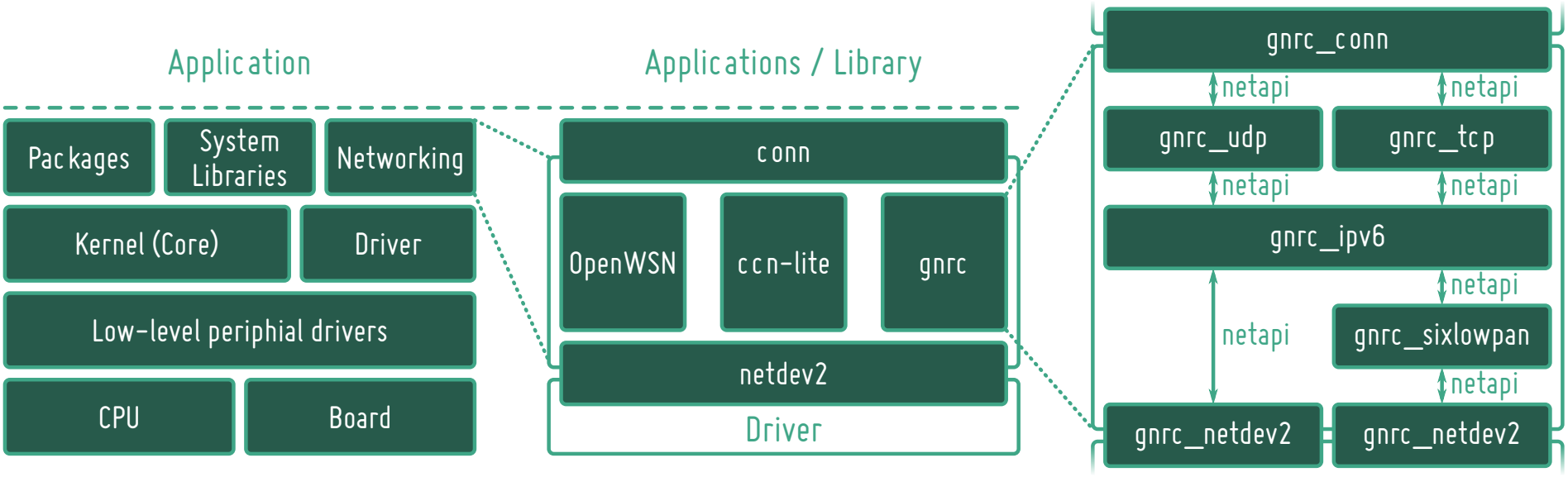
Architectural Overview



Design Decisions

- Efficient & Flexible Micro-Kernel
- System Level Interoperability
- Networking Interoperability

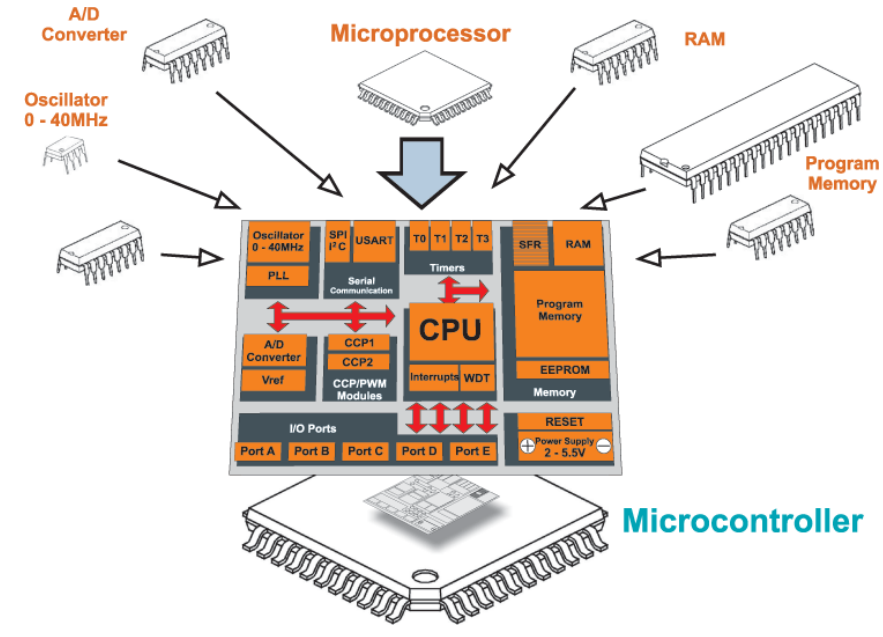
The Structure



Hardware Abstraction Layer (HAL)

Challenge: Support a Plethora of different Platforms

- Different Processor Architectures (8 bit, 16 bit, 32 bit . . .)
- Microcontroller[1] Peripherals
- Sensors and Actuators
- Network Devices
- Crypto Devices
- . . .



Source: MikroElektronika, https://www.mikroe.com

Goal: Provide a Common API

- Drivers for MCU Core
- Drivers for MCU Peripherals
- Device Drivers
- Timer API

[1] MicroController Unit (MCU)

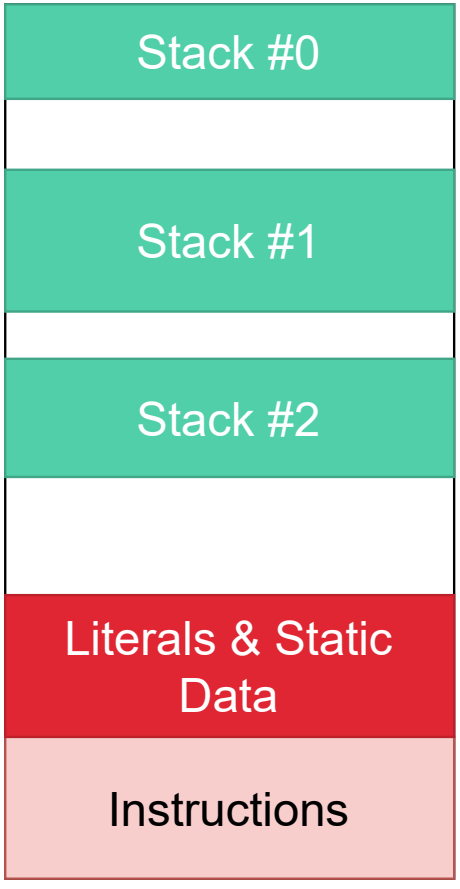
Multi-Threading

- Microkernel approach
  → But no Memory Protection
  ⇒ Stack Overflows are possible
- Provides Standard Multi-Threading
- Each Thread contains a (minimal) Thread Control Block (TCB)

Low Memory Usage

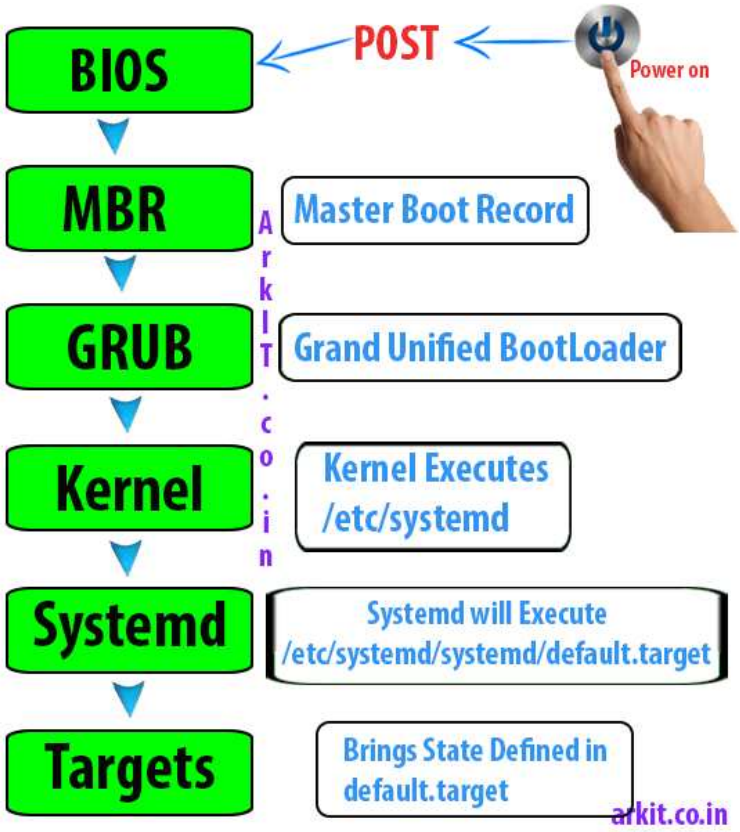
On a Low-end IoT Device (16-bit, 8 MHz):

- Min. TCB: 8 bytes
- Min. Stack Size: 96 bytes
- Up to 16,000 Messages/s (≙ 10,000 Packets/s for 802.15.4)



Boot Sequence

Linux Boot Sequence



Source: https://arkit.co.in/linux-boot-process-millionaire-guide/

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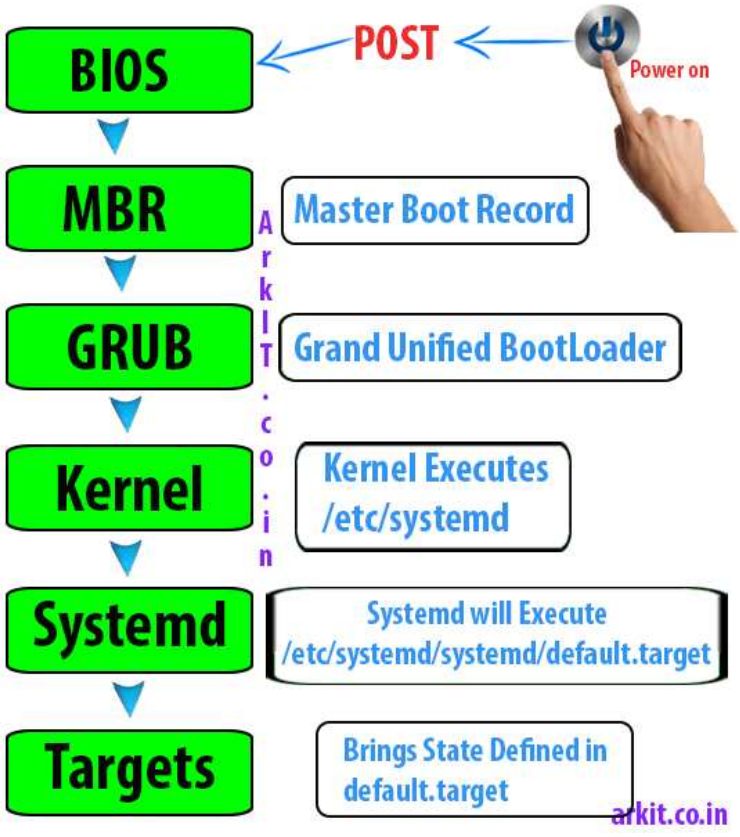
Linux Boot Sequence



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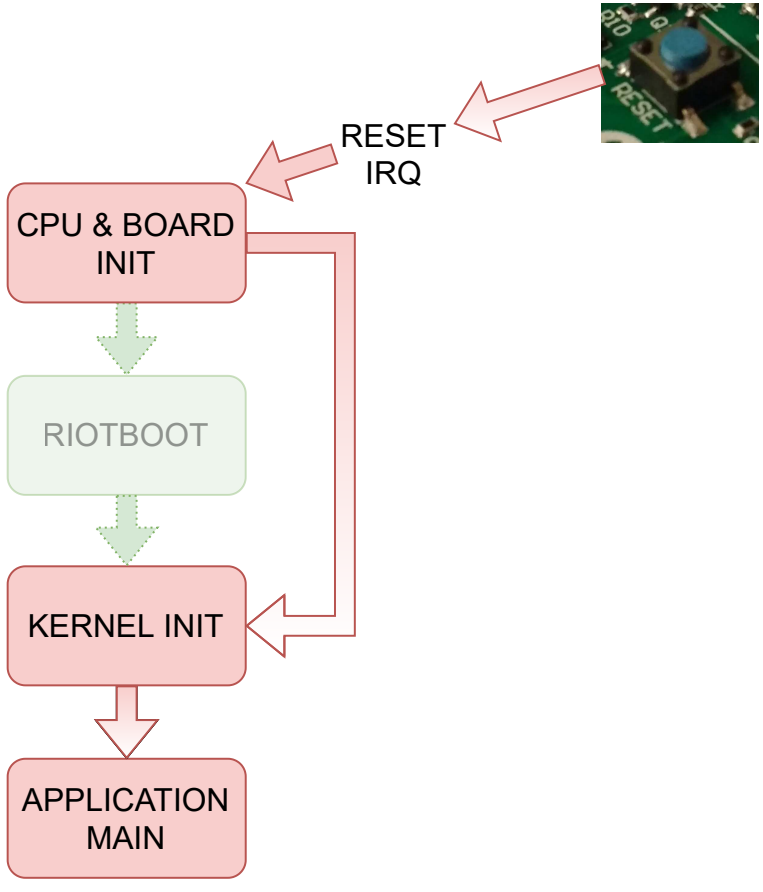
RIOT Boot Sequence



Scheduling

- Preemptive
- Threads have fixed Priorities
- The Thread in the Run-Queue with the highest Priority will run

A Periodic System Tick requires Timers

- A running Timer prevent the MCU to enter Deep Sleep Modes
- Periodic Wakeup waste Energy if there is nothing to do

Accounting for Real-Time Requirements

- All Data Structures in the Kernel have Static Size ⇒ All Operations are O(1)
- The Behavior of the Kernel is completely deterministic
- Interrupt Handlers are a short as possible

Source: Educación Física,

https://efsancristobalcartagena.blogspot.com

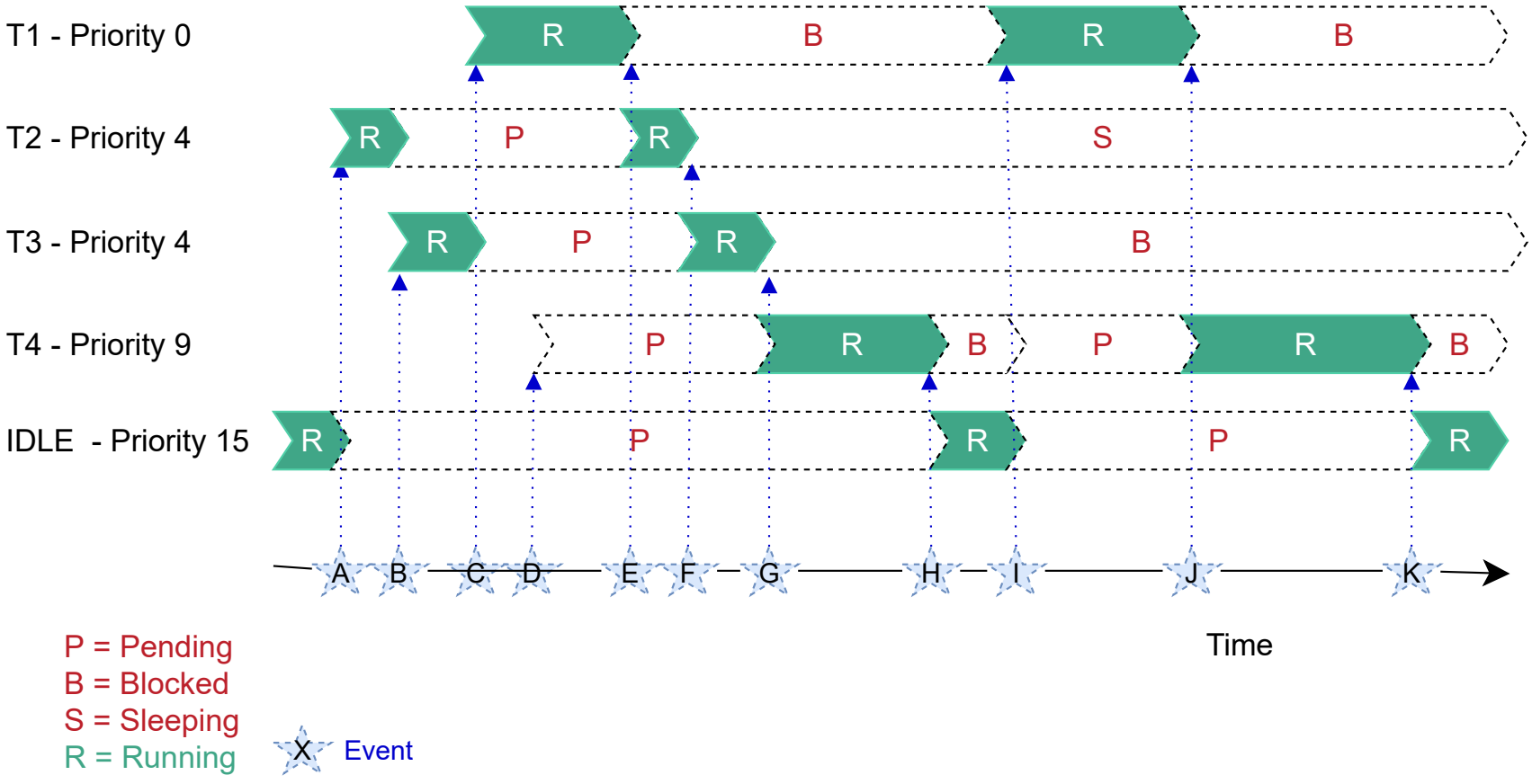
Thread States

- A Thread can have one of the following States:
  - Stopped
  - Sleeping
  - Blocked
  - Running
  - Pending
- The States `Running` and `Pending` indicate that the Thread is on the Run-Queue
  $\Rightarrow$ The Thread is ready to run

It may be blocked waiting for ...

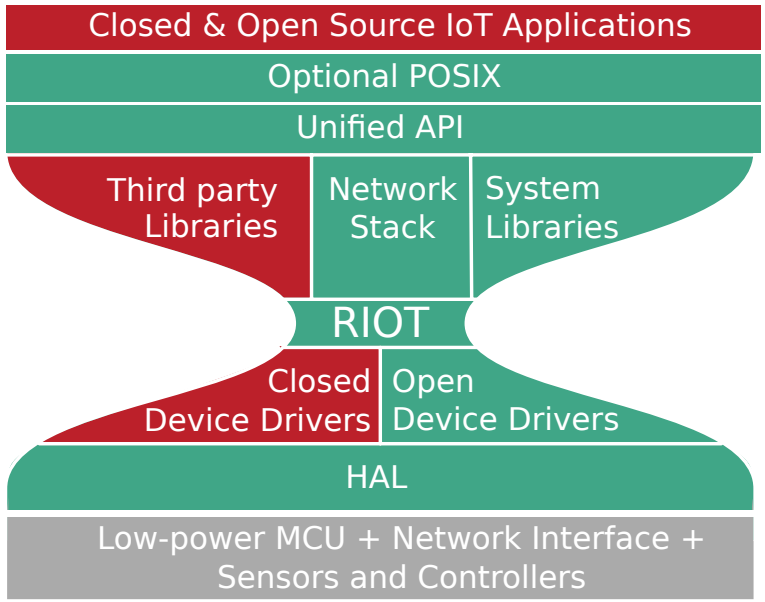
- a mutex
- a message to be received
- a message to be sent
- a response to a previous message
- a thread flag
- an action in its mailbox
- a condition variable

Scheduling example



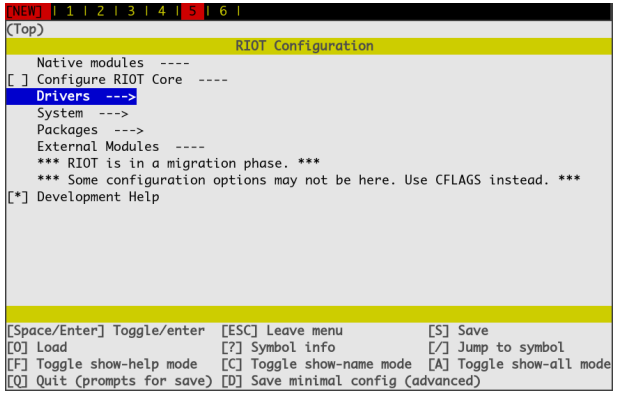
Application Programming Interface (API)

- Application shall be independent from the Hardware
- Portable Operating System Interface (POSIX) provides a common API among OS
- Not well suited for low-power IoT Devices
  - Origins from the 1980's
    $\longrightarrow$ Not very modern
  - Not tailored for constrained Resources
  - $\rightarrow$ But facilitates (initial) porting
- A POSIX-like API for this Class of Devices is missing so far



Modularity and Reusability

- Specialized Applications require only a Subset of the available Features
- Fine-grained Modularity is required to reduce the Binary Size
- Kernel Features may be disabled (→ Even Multi-Threading is optional)

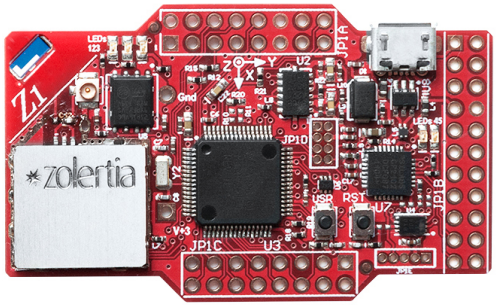


Result: Low Porting Effort

- Emulation support: RIOT as a Process
- Third-Party Development Tools
- Third-Party Library Packages

Package	Diff Size Overall	Relative
libcoap	639 lines	6.3 %
libfixmath	34 lines	0.2 %
lwip	767 lines	1.3 %
micro-ecc	14 lines	0.8 %
relic	24 lines	<0.1 %

Memory Comparison



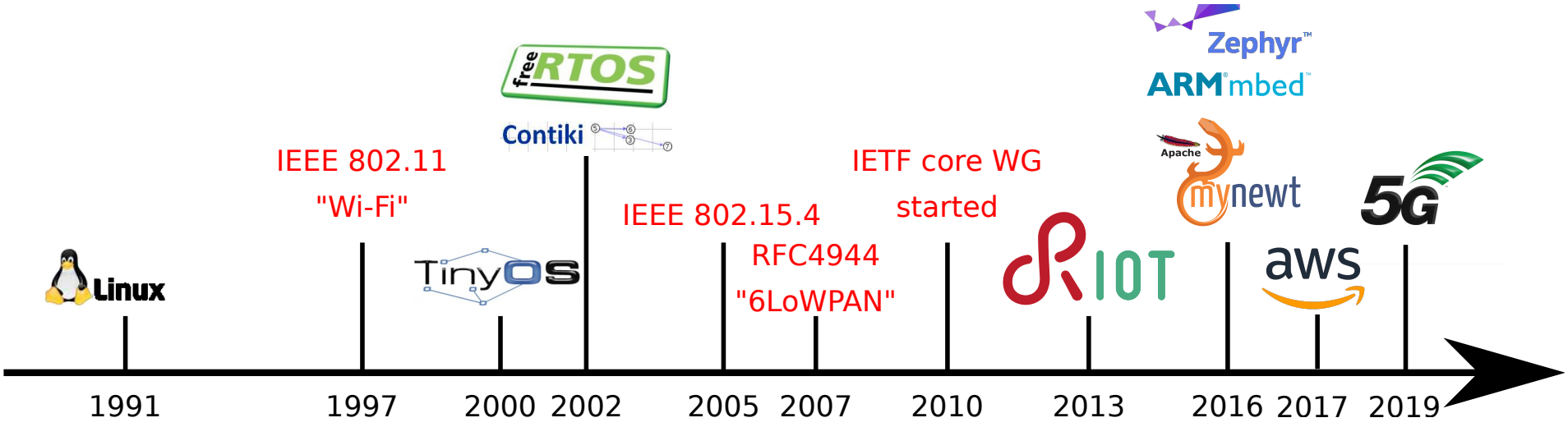
RIOT is as Small as Traditional WSN Operating Systems

Application	ROM	RAM
RIOT 2016.04	52,378	5,618
Contiki 3.0	51,562	5,530
TinyOS tinyos-main	40,574	6,812

Standard IoT IPv6 Networking Application

Code size comparison [Bytes] between RIOT, Contiki, and TinyOS.

Review & Perspectives



IoT Software in 2022

- Most popular IoT OS are:
  - RIOT
  - Zephyr
  - AWS FreeRTOS
- RIOT as the Linux for the IoT?
- ongoing challenges: Cloud integration, security, software updates

Agenda

9 Years of RIOT

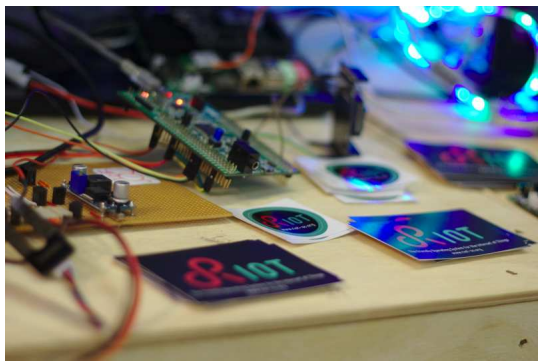
RIOT Open Source Development

- More Than 38,000 Commits and More Than 14,000 Pull Requests
- Over 1,800 forks on GitHub
- More Than 290 Contributors
- Support for More Than 230 Hardware Platforms
- Over 500 Scientific Publications

Get in touch!

- News: https://twitter.com/RIOT_OS and https://fosstodon.org/@RIOT_OS
- For Developers and Users: https://forum.riot-os.org
- Support & Discussions on Matrix: https://matrix.to/#/#riot-os:matrix.org
- Get the Source Code and Contribute: https://github.com/RIOT-OS/RIOT
- Show Cases: https://www.hackster.io/riot-os
- Videos on YouTube: https://www.youtube.com/c/RIOT-IoT
- Pics: https://www.flickr.com/people/142412063@N07/
- Get together at the yearly RIOT Summit: https://summit.riot-os.org
- Getting started with a tutorial on https://riot-os.github.io/riot-course/

GitHub



Literature

- E. Baccelli et al. “RIOT: An open source operating system for low-end embedded devices in the IoT,” IEEE Internet of Things Journal, December 2018.
- O. Hahm, “Enabling Energy Efficient Smart Object Networking at Internet-Scale,” Ecole Polytechnique, December 2016.
- O. Hahm, E. Baccelli, H. Petersen, and N. Tsiftes, “Operating Systems for Low-End Devices in the Internet of Things: a Survey,” IEEE Internet of Things Journal, October 2016.
- D. Lacamera, “Embedded Systems Architecture,” O’Reilly, May 2018.

Any Questions?